Overview

Yesterday we introduced equations to describe lines and planes in $\mathbb{R}^3$:

- $\mathbf{r} = \mathbf{r_0} + t\mathbf{v}$
  The vector equation for a line describes arbitrary points $\mathbf{r}$ in terms of a specific point $\mathbf{r_0}$ and the direction vector $\mathbf{v}$.
- $\mathbf{n} \cdot (\mathbf{r} - \mathbf{r_0}) = 0$
  The vector equation for a plane describes arbitrary points $\mathbf{r}$ in terms of a specific point $\mathbf{r_0}$ and the normal vector $\mathbf{n}$.

Question

How can we find the distance between a point and a plane in $\mathbb{R}^3$? Between two lines in $\mathbb{R}^3$? Between two planes? Between a plane and a line?

(From Stewart §10.5)

Distances in $\mathbb{R}^3$

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- To determine the distance between a point P and a line L, we need to find the point Q on L which is closest to P, and then measure the length of the line segment PQ.
  This line segment is *orthogonal* to L.
- To determine the distance between a point P and a plane S, we need to find the point Q on S which is closest to P, and then measure the length of the line segment PQ.
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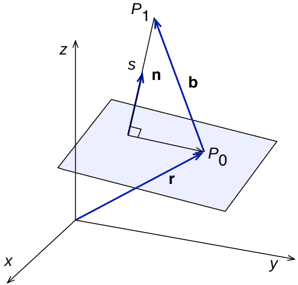
In both cases, the key to computing these distances is drawing a picture and using one of the vector product identitites.

Distance from a point to a plane

We find a formula for the distance s from a point $P_1 = (x_1, y_1, z_1)$ to the plane $Ax + By + Cz + D = 0$.



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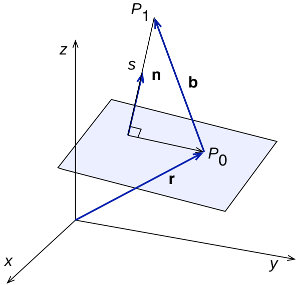

Let $P_0 = (x_0, y_0, z_0)$ be any point in the given plane and let **b** be the vector corresponding to $\vec{P_0P_1}$. Then

$$\mathbf{b} = \langle x_1 - x_0, y_1 - y_0, z_1 - z_0 \rangle.$$

The distance s from P_1 to the plane is equal to the absolute value of the scalar projection of **b** onto the normal vector $\mathbf{n} = \langle A, B, C \rangle$.

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$$\begin{aligned} s &= |\operatorname{comp}_{\mathbf{n}} \mathbf{b}| \\ &= \frac{|\mathbf{n} \cdot \mathbf{b}|}{||\mathbf{n}||} \\ &= \frac{|A(x_1 - x_0) + B(y_1 - y_0) + C(z_1 - z_0)|}{\sqrt{A^2 + B^2 + C^2}} \\ &= \frac{|Ax_1 + By_1 + Cz_1 - (Ax_0 + By_0 + Cz_0)|}{\sqrt{A^2 + B^2 + C^2}} \end{aligned}$$

Since P_0 is on the plane, its coordinates satisfy the equation of the plane and so we have $Ax_0 + By_0 + Cz_0 + D = 0$. Thus the formula for s can be written

$$s = \frac{|Ax_1 + By_1 + Cz_1 + D|}{\sqrt{A^2 + B^2 + C^2}}$$

Example 1

We find the distance from the point $(1, 2, 0)$ to the plane $3x - 4y - 5z - 2 = 0$.

From the result above, the distance s is given by

$$s = \frac{|Ax_0 + By_0 + Cz_0 + D|}{\sqrt{A^2 + B^2 + C^2}}$$

where $(x_0, y_0, z_0) = (1, 2, 0)$,

$$A = 3, B = -4, C = -5 \text{ and } D = -2.$$

This gives

$$\begin{aligned} s &= \frac{|3 \cdot 1 + (-4) \cdot 2 + (-5) \cdot 0 - 2|}{\sqrt{3^2 + (-4)^2 + (-5)^2}} \\ &= \frac{7}{\sqrt{50}} = \frac{7}{5\sqrt{2}} = \frac{7\sqrt{2}}{10}. \end{aligned}$$

Distance from a point to a line

Question

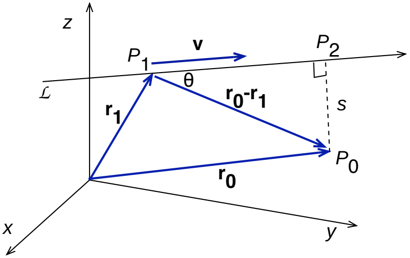
Given a point $P_0 = (x_0, y_0, z_0)$ and a line L in $\mathbb{R}^3$, what is the distance from P_0 to L?

Tools:

- describe L using vectors
- $||\mathbf{u} \times \mathbf{v}|| = ||\mathbf{u}||||\mathbf{v}|| \sin\theta$

Distance from a point to a line

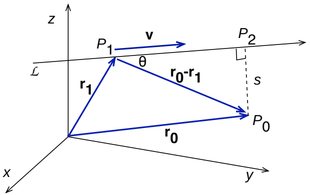
Let $P_0 = (x_0, y_0, z_0)$ and let L be the line through P_1 and parallel to the nonzero vector $\mathbf{v}$. Let $\mathbf{r}_0$ and $\mathbf{r}_1$ be the position vectors of P_0 and P_1 respectively. P_2 on L is the point closest to P_0 if and only if the vector $\overrightarrow{P_2P_0}$ is perpendicular to L.



The distance from P_0 to L is given by

$$s = ||\overrightarrow{P_2P_0}|| = ||\overrightarrow{P_1P_0}|| \sin\theta = ||\mathbf{r}_0 - \mathbf{r}_1|| \sin\theta$$

where θ is the angle between $\mathbf{r}_0 - \mathbf{r}_1$ and $\mathbf{v}$



$$s = ||\mathbf{r}_0 - \mathbf{r}_1|| \sin\theta$$

Since

$$||(\mathbf{r}_0 - \mathbf{r}_1) \times \mathbf{v}|| = ||\mathbf{r}_0 - \mathbf{r}_1|| \, ||\mathbf{v}|| \, \sin\theta$$

we get the formula

$$\begin{aligned} s &= ||\mathbf{r}_0 - \mathbf{r}_1|| \, \sin\theta \\ &= \frac{||(\mathbf{r}_0 - \mathbf{r}_1) \times \mathbf{v}||}{||\mathbf{v}||} \end{aligned}$$

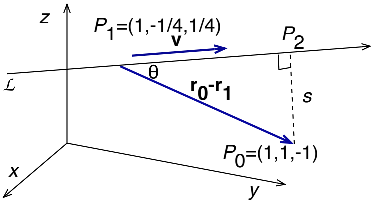
Example 2

Find the distance from the point $(1, 1, -1)$ to the line of intersection of the planes

$$x + y + z = 1, \quad 2x - y - 5z = 1.$$

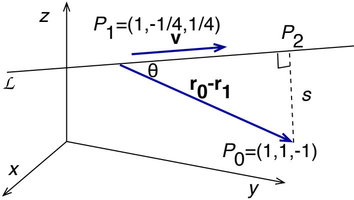
The direction of the line is given by $\mathbf{v} = \mathbf{n}_1 \times \mathbf{n}_2$ where $\mathbf{n}_1 = \mathbf{i} + \mathbf{j} + \mathbf{k}$, and $\mathbf{n}_2 = 2\mathbf{i} - \mathbf{j} - 5\mathbf{k}$.

$$\mathbf{v} = \mathbf{n}_1 \times \mathbf{n}_2 = -4\mathbf{i} + 7\mathbf{j} - 3\mathbf{k}.$$



In the diagram, P_1 is an arbitrary point on the line. To find such a point, put $x = 1$ in the first equation. This gives $y = -z$ which can be used in the second equation to find $z = 1/4$, and hence $y = -1/4$.

Here $\overrightarrow{P_1P_0} = \mathbf{r}_0 - \mathbf{r}_1 = \frac{5}{4}\mathbf{j} - \frac{5}{4}\mathbf{k}$. So



$$\begin{aligned}
s &= \frac{||(\mathbf{r}_0 - \mathbf{r}_1)\times\mathbf{v}||}{||\mathbf{v}||} \\
&= \frac{||(\frac{5}{4}\mathbf{j} - \frac{5}{4}\mathbf{k})\times(-4\mathbf{i} + 7\mathbf{j} - 3\mathbf{k})||}{\sqrt{(-4)^2 + 7^2 + (-3)^2}} \\
&= \frac{||5\mathbf{i} + 5\mathbf{j} + 5\mathbf{k}||}{\sqrt{74}} \\
&= \sqrt{\frac{75}{74}}.
\end{aligned}$$

Distance between two lines

Let L_1 and L_2 be two lines in $\mathbb{R}^3$ such that

- L_1 passes through the point P_1 and is parallel to the vector $\mathbf{v}_1$
- L_2 passes through the point P_2 and is parallel to the vector $\mathbf{v}_2$.

Let $\mathbf{r}_1$ and $\mathbf{r}_2$ be the position vectors of P_1 and P_2 respectively.
Then parametric equation for these lines are

$$L_1 \qquad \mathbf{r} = \mathbf{r}_1 + t\mathbf{v}_1$$

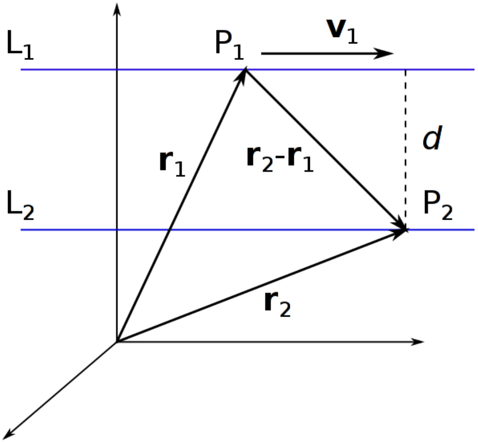
$$L_2 \qquad \tilde{\mathbf{r}} = \mathbf{r}_2 + s\mathbf{v}_2$$

Note that $\mathbf{r}_2 - \mathbf{r}_1 = \overrightarrow{P_1P_2}$.
We want to compute the smallest distance d (simply called the distance) between the two lines.
If the two lines intersect, then $d = 0$. If the two lines do not intersect we can distinguish two cases.

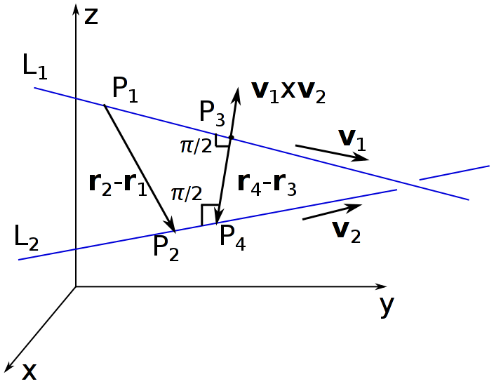
Case 1: L_1 and L_2 are parallel and do not intersect.

In this case the distance d is simply the distance from the point P_2 to the line L_1 and is given by

$$d = \frac{||\overrightarrow{P_1P_2} \times \mathbf{v}_1||}{||\mathbf{v}_1||} = \frac{||(\mathbf{r}_2 - \mathbf{r}_1) \times \mathbf{v}_1||}{||\mathbf{v}_1||}$$



Case 2: L_1 and L_2 are skew lines.



If P_3 and P_4 (with position vectors $\mathbf{r}_3$ and $\mathbf{r}_4$ respectively) are the points on L_1 and L_2 that are closest to one another, then the vector $\overrightarrow{P_3P_4}$ is perpendicular to both lines (i.e. to both $\mathbf{v}_1$ and $\mathbf{v}_2$) and therefore parallel to $\mathbf{v}_1 \times \mathbf{v}_2$. The distance d is the length of $\overrightarrow{P_3P_4}$.

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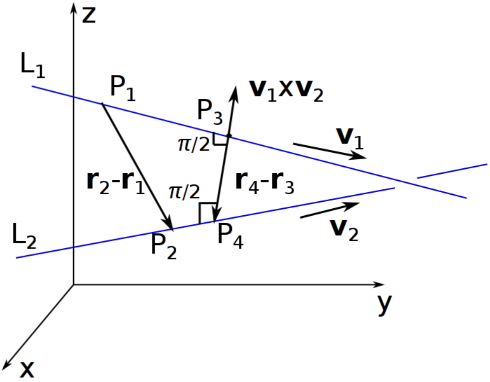

Now $\overrightarrow{P_3P_4} = \mathbf{r}_4 - \mathbf{r}_3$ is the vector projection of $\overrightarrow{P_1P_2} = \mathbf{r}_2 - \mathbf{r}_1$ along $\mathbf{v}_1 \times \mathbf{v}_2$.

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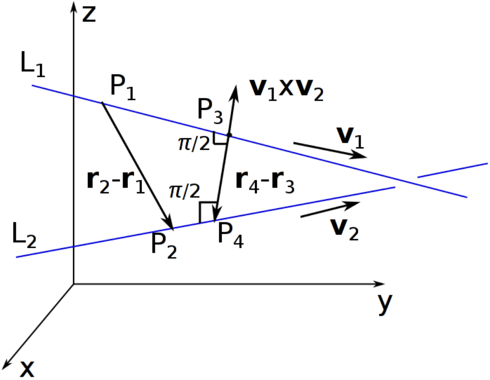

Thus the distance d is the absolute value of the scalar projection of $\mathbf{r}_2 - \mathbf{r}_1$ along $\mathbf{v}_1 \times \mathbf{v}_2$

$$d = ||\mathbf{r}_4 - \mathbf{r}_3|| = \frac{|(\mathbf{r}_2 - \mathbf{r}_1) \cdot (\mathbf{v}_1 \times \mathbf{v}_2)|}{||\mathbf{v}_1 \times \mathbf{v}_2||}$$

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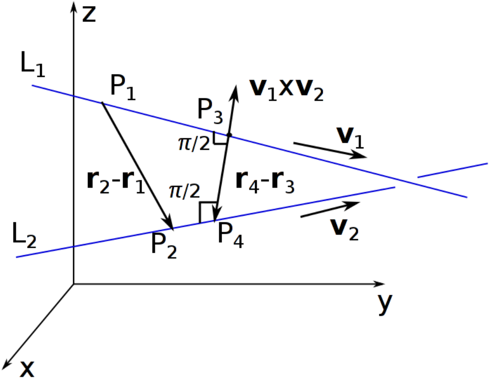

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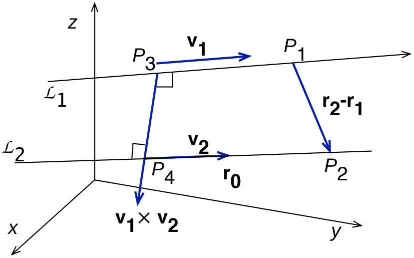
Observe that if the two lines are parallel then $\mathbf{v}_1$ and $\mathbf{v}_2$ are proportional and thus $\mathbf{v}_1 \times \mathbf{v}_2 = \mathbf{0}$ (the zero vector) and the above formula does not make sense.

Example 3

Find the distance between the skew lines

$$\begin{cases} x + 2y = 3 \\ y + 2z = 3 \end{cases} \quad \text{and} \quad \begin{cases} x + y + z = 6 \\ x - 2z = -5 \end{cases}$$



We can take $P_1 = (1, 1, 1)$, a point on the first line, and $P_2 = (1, 2, 3)$ a point on the second line. This gives $\mathbf{r}_2 - \mathbf{r}_1 = \mathbf{j} + 2\mathbf{k}$.

Now we need to find $\mathbf{v}_1$ and $\mathbf{v}_2$:

$$\mathbf{v}_1 = (\mathbf{i} + 2\mathbf{j})\times(\mathbf{j} + 2\mathbf{k}) = 4\mathbf{i} - 2\mathbf{j} + \mathbf{k},$$

and

$$\mathbf{v}_2 = (\mathbf{i} + \mathbf{j} + \mathbf{k})\times(\mathbf{i} - 2\mathbf{k}) = -2\mathbf{i} + 3\mathbf{j} - \mathbf{k}.$$

This gives

$$\mathbf{v}_1\times\mathbf{v}_2 = -\mathbf{i} + 2\mathbf{j} + 8\mathbf{k}.$$

The required distance d is the length of the projection of $\mathbf{r}_2 - \mathbf{r}_1$ in the direction of $\mathbf{v}_1\times\mathbf{v}_2$, and is given by

$$\begin{aligned} d &= \frac{|(\mathbf{r}_2 - \mathbf{r}_1)\cdot(\mathbf{v}_1\times\mathbf{v}_2)|}{||\mathbf{v}_1\times\mathbf{v}_2||} \\ &= \frac{|(\mathbf{j} + 2\mathbf{k})\cdot(-\mathbf{i} + 2\mathbf{j} + 8\mathbf{k})|}{\sqrt{(-1)^2 + 2^2 + 8^2}} \\ &= \frac{18}{\sqrt{69}}. \end{aligned}$$