Overview

Before the break, we began to study eigenvectors and eigenvalues, introducing the characteristic equation as a tool for finding the eigenvalues of a matrix:

 $\det(A - \lambda I) = 0.$

The roots of the characteristic equation are the eigenvalues of λ . We also discussed the notion of similarity: the matrices A and B are similar if $A = PBP^{-1}$ for some invertible matrix P.

Question

When is a matrix A similar to a diagonal matrix?

From Lay, §5.3

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Quick review

Definition

An *eigenvector* of an $n \times n$ matrix A is a non-zero vector \mathbf{x} such that $A\mathbf{x} = \lambda \mathbf{x}$ for some scalar λ . The scalar λ is an *eigenvalue* for A.

To find the eigenvalues of a matrix, find the solutions of the characteristic equation:

 $\det(A - \lambda I) = \mathbf{0}.$

The λ -eigenspace is the set of all eigenvectors for the eigenvalue λ , together with the zero vector. The λ -eigenspace E_{λ} is Nul $(A - \lambda I)$.

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The advantages of a diagonal matrix

Given a diagonal matrix, it's easy to answer the following questions:

() What are the eigenvalues of *D*? The dimensions of each eigenspace?

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- What is the determinant of D?
- Is D invertible?
- What is the characteristic polynomial of *D*?
- **(a)** What is D^k for k = 1, 2, 3, ...?

For example, let $D = \begin{bmatrix} 10^{50} & 0 & 0 \\ 0 & \pi & 0 \\ 0 & 0 & -2.7 \end{bmatrix}$.

Can you answer each of the questions above?

The diagonalisation theorem

The goal in this section is to develop a useful factorisation $A = PDP^{-1}$, for an $n \times n$ matrix A. This factorisation has several advantages:

- it makes transparent the geometric action of the associated linear transformation, and
- it permits easy calculation of A^k for large values of k:

Example 1 Let $D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & -4 & 0 \\ 0 & 0 & -1 \end{bmatrix}$.

Then the transformation T_D scales the three standard basis vectors by 2, -4, and -1, respectively.

$$D^7 = egin{bmatrix} 2^7 & 0 & 0 \ 0 & (-4)^7 & 0 \ 0 & 0 & (-1)^7 \end{bmatrix}$$

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Example 2

Let $A = \begin{bmatrix} 1 & 3 \\ 2 & 2 \end{bmatrix}$. We will use similarity	to find a formula for A^k . Suppose
we're given $A = PDP^{-1}$ where $P = \begin{bmatrix} 1\\ 1 \end{bmatrix}$	$\begin{bmatrix} 3 \\ -2 \end{bmatrix} \text{ and } D = \begin{bmatrix} 4 & 0 \\ 0 & -1 \end{bmatrix}.$

We have

$$A = PDP^{-1}$$

$$A^{2} = PDP^{-1}PDP^{-1}$$

$$= PD^{2}P^{-1}$$

$$A^{3} = PD^{2}P^{-1}PDP^{-1}$$

$$= PD^{3}P^{-1}$$

$$\vdots \qquad \vdots$$

$$A^{k} = PD^{k}P^{-1}$$

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So

$$\begin{aligned} A^{k} &= \begin{bmatrix} 1 & 3 \\ 1 & -2 \end{bmatrix} \begin{bmatrix} 4^{k} & 0 \\ 0 & (-1)^{k} \end{bmatrix} \begin{bmatrix} 2/5 & 3/5 \\ 1/5 & -1/5 \end{bmatrix} \\ &= \begin{bmatrix} \frac{2}{5}4^{k} + \frac{3}{5}(-1)^{k} & \frac{3}{5}4^{k} - \frac{3}{5}(-1)^{k} \\ \frac{3}{5}4^{k} - \frac{2}{5}(-1)^{k} & \frac{3}{5}4^{k} + \frac{2}{5}(-1)^{k} \end{bmatrix} \end{aligned}$$

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Diagonalisable Matrices

Definition

An $n \times n$ (square) matrix is **diagonalisable** if there is a diagonal matrix D such that A is similar to D.

That is, A is diagonalisable if there is an invertible $n \times n$ matrix P such that $P^{-1}AP = D$ (or equivalently $A = PDP^{-1}$).

Question

How can we tell when A is diagonalisable?

The answer lies in examining the eigenvalues and eigenvectors of A.

Recall that in Example 2 we had

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 2 \end{bmatrix}, D = \begin{bmatrix} 4 & 0 \\ 0 & -1 \end{bmatrix} \text{ and } P = \begin{bmatrix} 1 & 3 \\ 1 & -2 \end{bmatrix} \text{ and } A = PDP^{-1}.$$

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Note that

$$A\begin{bmatrix}1\\1\end{bmatrix} = \begin{bmatrix}1 & 3\\2 & 2\end{bmatrix}\begin{bmatrix}1\\1\end{bmatrix} = 4\begin{bmatrix}1\\1\end{bmatrix}$$

and

$$A\begin{bmatrix}3\\-2\end{bmatrix} = \begin{bmatrix}1 & 3\\2 & 2\end{bmatrix}\begin{bmatrix}3\\-2\end{bmatrix} = -1\begin{bmatrix}3\\-2\end{bmatrix}.$$

We see that each column of the matrix P is an eigenvector of A...

This means that we can view P as a change of basis matrix from eigenvector coordinates to standard coordinates!

In general, if AP = PD, then

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$$A\begin{bmatrix}\mathbf{p}_1 & \mathbf{p}_2 & \cdots & \mathbf{p}_n\end{bmatrix} = \begin{bmatrix}\mathbf{p}_1 & \mathbf{p}_2 & \cdots & \mathbf{p}_n\end{bmatrix} \begin{bmatrix}\lambda_1 & 0 & \cdots & 0\\ 0 & \lambda_2 & \cdots & 0\\ \vdots & \vdots & \ddots & \vdots\\ 0 & 0 & \cdots & \lambda_n\end{bmatrix}.$$

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If $\begin{bmatrix} \mathbf{p}_1 & \mathbf{p}_2 & \cdots & \mathbf{p}_n \end{bmatrix}$ is invertible, then A is the same as

$$\begin{bmatrix} \mathbf{p}_1 & \mathbf{p}_2 & \cdots & \mathbf{p}_n \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{bmatrix} \begin{bmatrix} \mathbf{p}_1 & \mathbf{p}_2 & \cdots & \mathbf{p}_n \end{bmatrix}^{-1}.$$